

## Vector calculus

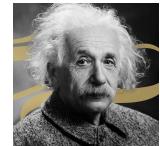
Consider a scalar  $A$  (like temperature) or a vector  $\vec{A}$  (like electric field) defined in 3-dim space ( $x, y, z$ )

$$A(\vec{x}) = A(x, y, z)$$

$$\vec{A}(\vec{x}) = \hat{e}_1 A_1(\vec{x}) + \hat{e}_2 A_2(\vec{x}) + \hat{e}_3 A_3(\vec{x}) = \sum_{j=1,2,3} \hat{e}_j A_j \equiv \hat{e}_j A_j = \hat{e}_k A_k$$

Inner product:  $\vec{A} \cdot \vec{B} = A_i B_i$

sum over  
repeated indexes



I said so

Gradient operator  $\vec{\nabla} \equiv \hat{e}_i \partial_i = (\partial_x, \partial_y, \partial_z)$

$\vec{\nabla} A = \hat{e}_i \partial_i A = (\partial_x A, \partial_y A, \partial_z A)$  is a vector that indicates the shortest path to go up.

Divergence  $\vec{\nabla} \cdot \vec{A} = (\partial_x, \partial_y, \partial_z) \cdot (A_x, A_y, A_z) = \partial_i A_i$  is a scalar that indicates if any source ( $\vec{\nabla} \cdot \vec{A} > 0$ ) or sink ( $\vec{\nabla} \cdot \vec{A} < 0$ )

$$\begin{aligned} \text{Curl } \vec{\nabla} \times \vec{A} &\equiv \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ \partial_x & \partial_y & \partial_z \\ A_x & A_y & A_z \end{vmatrix} = \hat{e}_x (\partial_y A_z - \partial_z A_y) + \hat{e}_y (\partial_z A_x - \partial_x A_z) + \\ &\quad \hat{e}_z (\partial_x A_y - \partial_y A_x) \\ &\equiv \epsilon_{ijk} \hat{e}_i \partial_j A_k \text{ (sum over repeated i, j, k)} \end{aligned}$$

Levi-Civita symbol

$\epsilon_{ijk} = 1$  if  $(ijk)$  is an even permutation of  $(1, 2, 3)$   $\Rightarrow \epsilon_{123} = \epsilon_{231} = \epsilon_{312} = 1$

$\epsilon_{ijk} = -1$  if  $(ijk)$  is an odd permutation of  $(1, 2, 3)$   $\Rightarrow \epsilon_{213} = \epsilon_{321} = \epsilon_{132} = -1$

$\epsilon_{ijk} = 0$  if there is any repeated indexes  $\Rightarrow \epsilon_{122} = \epsilon_{333} = \dots = 0$

$$\begin{aligned} \text{Example } \vec{A} \times \vec{B} &= \epsilon_{ijk} \hat{e}_i A_j B_k = \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \epsilon_{ijk} \hat{e}_i A_j B_k \\ \vec{\nabla} \times \vec{A} &= \epsilon_{ijk} \hat{e}_i \partial_j A_k = \sum_{i=1}^3 \hat{e}_i \underbrace{\epsilon_{ijk}}_{+} \partial_j A_k \end{aligned}$$

$$\text{Now the most useful relation: } \underbrace{\epsilon_{ijk} \epsilon_{ilm}}_{=} = \delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}$$

$$\begin{aligned} \text{Laplacian } \vec{\nabla}^2 A &= \vec{\nabla} \cdot \vec{\nabla} A = \hat{e}_i \partial_i (\vec{\nabla} A) = (\hat{e}_i \partial_i) \cdot (\hat{e}_j \partial_j A) \\ &= \delta_{ij} \partial_i \partial_j A = \partial_i \partial_i A = \partial_x^2 A + \partial_y^2 A + \partial_z^2 A \end{aligned}$$

$$\hat{e}_i \cdot \hat{e}_j = \delta_{ij} = 1 \text{ when } i=j = 0 \text{ when } i \neq j$$

Exercise:

Prove  $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$      $\hat{\epsilon}_{\ell} \partial_{\ell} \epsilon_{ijk} \hat{\epsilon}_i \partial_j A_k = \epsilon_{ijk} \hat{\epsilon}_{\ell} \cdot \hat{\epsilon}_i \partial_{\ell} \partial_j A_k = \epsilon_{ijk} \underline{\partial_i \partial_j} A_k = 0$

$\vec{\nabla} \times \vec{\nabla} A = 0$      $\epsilon_{ijk} \hat{\epsilon}_i \partial_j (\vec{\nabla} A)_k = \epsilon_{ijk} \hat{\epsilon}_i \partial_j \partial_k A_k = 0$

$$\begin{aligned}\vec{\nabla} \cdot (\vec{A} \times \vec{B}) &= \vec{B} \cdot \vec{\nabla} \times \vec{A} - \vec{A} \cdot \vec{\nabla} \times \vec{B} & \hat{\epsilon}_i \partial_i (\epsilon_{jkl} \hat{\epsilon}_j A_k B_l) \\&= \hat{\epsilon}_i \hat{\epsilon}_j \epsilon_{jkl} \partial_i (A_k B_l) \\&= \delta_{ij} \epsilon_{jkl} (A_k \partial_i B_l + B_l \partial_j A_k) \\&= \epsilon_{jkl} (A_k \partial_j B_l + B_l \partial_j A_k) \\&= A_k \epsilon_{jkl} \partial_j B_l + B_l \epsilon_{jkl} \partial_j A_k \\&= -A_k \epsilon_{kjl} \partial_j B_l + B_l \epsilon_{ljk} \partial_j A_k \\&= \vec{B} \cdot \vec{\nabla} \times \vec{A} - \vec{A} \cdot \vec{\nabla} \times \vec{B}\end{aligned}$$

$$\begin{aligned}\vec{\nabla} \times (\vec{A} \times \vec{B}) &= (\vec{B} \cdot \vec{\nabla}) A + A (\vec{\nabla} \cdot \vec{B}) - (A \cdot \vec{\nabla}) B - B (\vec{\nabla} \cdot \vec{A}) \\&= \epsilon_{ijk} \hat{\epsilon}_i \partial_j (\vec{A} \times \vec{B})_k \\&= \epsilon_{ijk} \epsilon_{kem} \hat{\epsilon}_i \partial_j (A_e B_m) \\&= \epsilon_{kij} \epsilon_{kem} \hat{\epsilon}_i (A_e \partial_j B_m + B_m \partial_j A_e) \\&= (\delta_{ie} \delta_{jm} - \delta_{im} \delta_{je}) \\&= \hat{\epsilon}_i (A_i \partial_j B_j + B_j \partial_j A_i - A_e \partial_e B_i - B_i \partial_j A_j) \\&= \vec{A} \vec{\nabla} \cdot \vec{B} + (\vec{B} \cdot \vec{\nabla}) \vec{A} - (\vec{A} \cdot \vec{\nabla}) \vec{B} - \vec{B} (\vec{\nabla} \cdot \vec{A})\end{aligned}$$