

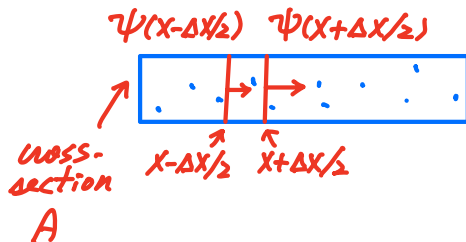
Longitudinal waves: Sound wave in gas, liquid, and solid.

step 1: What is the equilibrium state?

step 2: What's the restoring force?

step 3: Associate the force with the motion of neighbors.

Consider a uniform medium with mass density ρ



$$ma = \rho \Delta V \ddot{\psi} = \rho A \Delta x \ddot{\psi}$$

$$F = AP(x - \Delta x/2) - AP(x + \Delta x/2) \\ = -A \Delta x P'(x)$$

In gas and liquid $P > 0$
In solid $P < 0$

What is the origin of restoring force?

Let's introduce compressibility $\beta \equiv -\frac{1}{V} \frac{\partial V}{\partial P}$ ($= \frac{1}{\text{stiffness}}$)

$$\Delta P = -\frac{1}{\beta} \frac{\Delta V}{V} = -\frac{1}{\beta} \frac{A [\psi(x + \Delta x/2) - \psi(x - \Delta x/2)]}{A \Delta x}$$

$$\Rightarrow P(x) - P_0 = -\frac{1}{\beta} \psi'(x)$$

Pressure in equilibrium

$$\rho = \frac{\rho_0 V}{V + \Delta V} = \rho_0 \left(1 + \frac{\Delta V}{V}\right)^{-1} \approx \rho_0 [1 - \psi'(x)]$$

Thus we have $\rho A \Delta x \ddot{\psi} = -A \Delta x \left(-\frac{1}{\beta} \partial_x \psi\right)$

$$\Rightarrow \rho \ddot{\psi} = \frac{1}{\beta} \partial_x \psi \quad \text{or} \quad \ddot{\psi} = v^2 \partial_x \psi$$

$$\Rightarrow v = \sqrt{1/\rho\beta}$$

For an ideal gas:

$$PV = NKT. \text{ For } T = \text{const. } \beta = -\frac{1}{V} \frac{\partial V}{\partial P} = \frac{1}{V} \frac{NKT}{P^2} = \frac{1}{\rho kT}$$

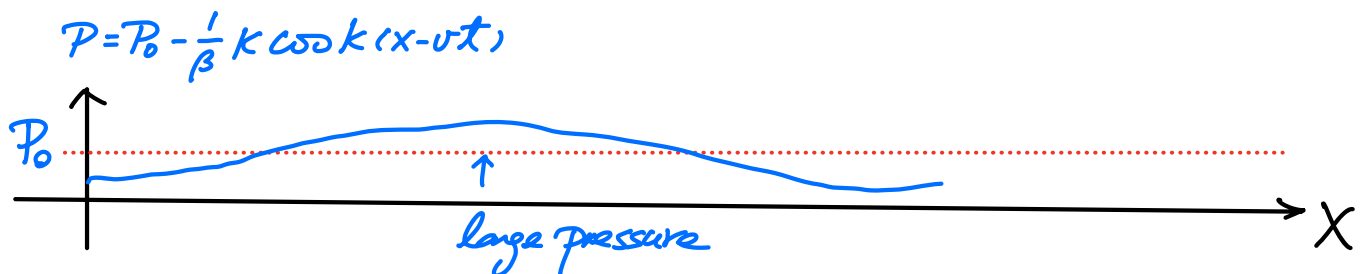
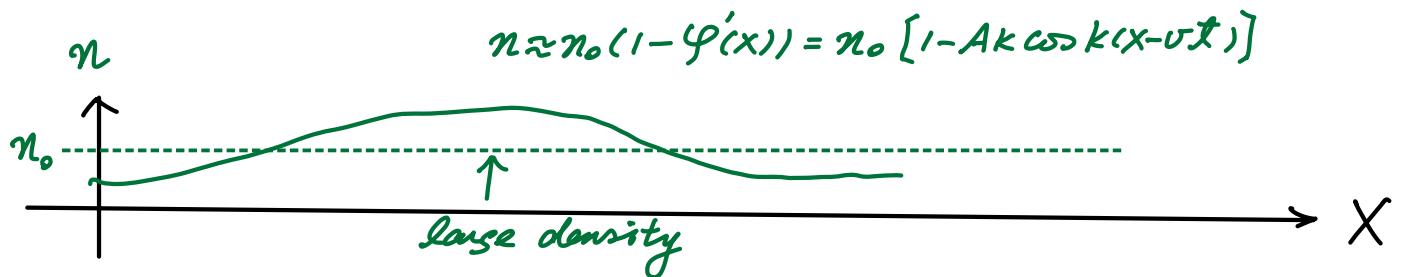
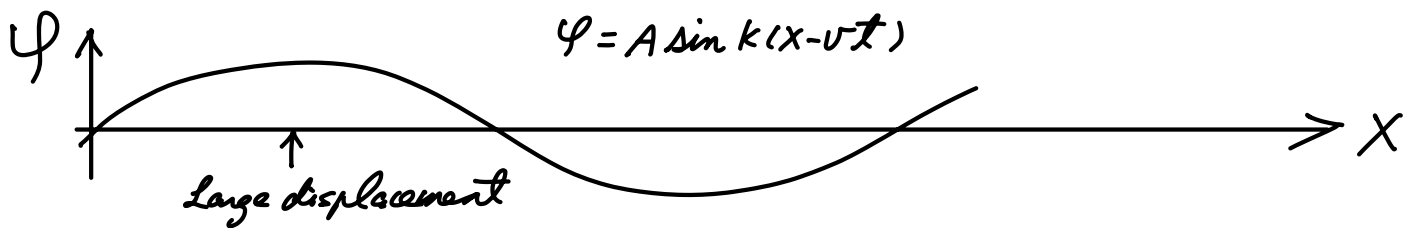
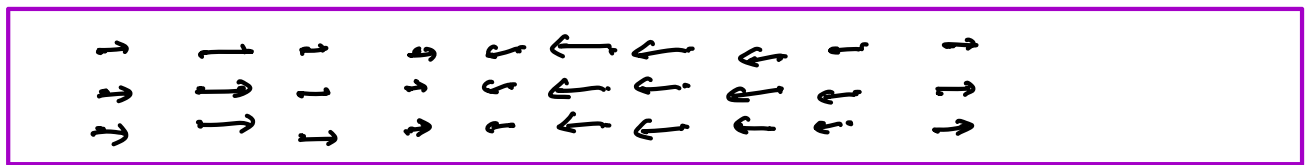
$$\Rightarrow v = \sqrt{kT} = \sqrt{\partial P / \partial \rho}$$

Faster sound for lower density and lower compressibility

Let's compare air ^{340 m/s} water ^{1500 m/s} ice ^{4000 m/s}

n	small	high	higher
β	high	low	lower

Microscopic picture



Electromagnetic waves

Maxwell Eqns in medium $\nabla \cdot \vec{E} = \rho/\epsilon = 0$ Gauss' law

$\nabla \cdot \vec{B} = 0$ no mag. monopoles

$\nabla \times \vec{E} = -\partial_t \vec{B}$ Faraday's law

$\nabla \times \vec{B} = \mu \epsilon \partial_t \vec{E} + \mu_0 \vec{j} = \mu \epsilon \partial_t \vec{E}$ Amp-Max. law

$$\left. \begin{aligned} \nabla \times (\nabla \times \vec{E}) &= \nabla (\nabla \cdot \vec{E}) - (\nabla \cdot \nabla) \vec{E} = -\nabla^2 \vec{E} \\ &= -\partial_t \nabla \times \vec{B} = -\mu \epsilon \partial_t^2 \vec{E} \end{aligned} \right\} \partial_t^2 \vec{E} = \frac{1}{\mu \epsilon} \nabla^2 \vec{E} \quad v = \frac{1}{\sqrt{\mu \epsilon}}$$

Similarly $\partial_t^2 \vec{B} = \frac{1}{\mu \epsilon} \nabla^2 \vec{B}$

In vacuum $\partial_t^2 \begin{Bmatrix} \vec{E} \\ \vec{B} \end{Bmatrix} = \frac{1}{\mu_0 \epsilon_0} \begin{Bmatrix} \vec{E} \\ \vec{B} \end{Bmatrix} \quad v = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c \Rightarrow \text{index of refraction } n = \frac{c}{v} = \sqrt{\frac{\mu \epsilon}{\mu_0 \epsilon_0}}$

We may think the solution is $\vec{E}(\vec{x}, t) = \sum_k \vec{A}(\vec{k} \cdot \vec{x} - \omega_k t) \quad \omega_k = v |\vec{k}|$

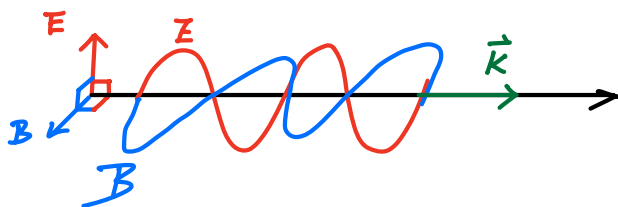
But the other Maxwell eqns provide further restriction

$\vec{E}(\vec{x}, t) = \vec{E} e^{i\vec{k} \cdot (\vec{x} - c\vec{t})} = E_j \hat{e}_j e^{ik_x x} e^{-i\omega t}$

Gauss' law $\nabla \cdot \vec{E} = \partial_j E_j e^{ik_x x} e^{-i\omega t} = \vec{k} \cdot \vec{E} = 0$

$\nabla \cdot \vec{B} = \partial_j B_j e^{ik_x x} e^{-i\omega t} = \vec{k} \cdot \vec{B} = 0$

Faraday's law $\nabla \times \vec{E} = -\partial_t \vec{B} \Rightarrow i\vec{k} \times \vec{E} = -(-i\omega) \vec{B} \Rightarrow \hat{k} \times \vec{E} = v \vec{B}$



Forward $\vec{E}^+ = (E, 0, 0) e^{ik(z-ct)}$
 $\vec{B}^+ = (0, E/c, 0) e^{ik(z-ct)}$

backward $\vec{E}^- = (E, 0, 0) e^{ik(-z-ct)}$
 $\vec{B}^- = (0, -E/c, 0) e^{ik(-z-ct)}$

Standing waves: $\vec{E} = \vec{E}^+ + \vec{E}^- = (E, 0, 0) [\omega k(z-ct) + \omega k(-z-ct)]$
 $= (2E, 0, 0) \omega k z \cos \omega t$
 $\vec{B} = \vec{B}^+ + \vec{B}^- = (0, 2E/c, 0) [\omega k(z-ct) - \omega k(-z-ct)]$
 $= (0, 2E/c, 0) \sin kz \sin \omega t$